Beyond Porting

How Modern OpenGL can Radically Reduce Driver



Who are we?



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What will we cover?



Dynamic Buffer Generation
 Efficient Texture Management
 Increasing Draw Call Count

Dynamic Buffer Generation



Problem

- Our goal is to generate dynamic geometry directly in place.
- It will be used one time, and will be completely regenerated next frame.
 - Particle systems are the most common example
 - Vegetation / foliage also common



Typical Solution



```
void UpdateParticleData(uint dstBuf) {
  BindBuffer(ARRAY BUFFER, dstBuf);
  access = MAP UNSYNCHRONIZED | MAP WRITE BIT;
  for particle in allParticles {
    dataSize = GetParticleSize(particle);
    void* dst = MapBuffer(ARRAY BUFFER, offset, dataSize, access);
    (*(Particle*)dst) = *particle;
    UnmapBuffer(ARRAY BUFFER);
    offset += dataSize;
```

// Now render with everything.

}

};

The horror



```
void UpdateParticleData(uint dstBuf) {
  BindBuffer (ARRAY BUFFER, dstBuf);
  access = MAP UNSYNCHRONIZED | MAP WRITE BIT;
  for particle in allParticles {
    dataSize = GetParticleSize(particle);
    void* dst = MapBuffer(ARRAY BUFFER, offset, dataSize, access);
    (*(Particle*)dst) = *particle;
    UnmapBuffer (ARRAY BUFFER);
                                         This is so slow.
    offset += dataSize;
```

// Now render with everything.



First, a quick interlude on modern GL drivers
 In the application (client) thread, the driver is very thin.

 It simply packages work to hand off to the server thread.

 The server thread does the real processing

 It turns command sequences into push buffer fragments.

Healthy Driver Interaction Visualized



Application Driver (Client) Driver (Server) GPU

Thread separator
 Component separator



MAP_UNSYNCHRONIZED



Avoids an application-GPU sync point (a CPU-GPU sync point)

But causes the Client and Server threads to serialize

- This forces all pending work in the server thread to complete
- It's quite expensive (almost always needs to be avoided)

Healthy Driver Interaction Visualized



Application Driver (Client) Driver (Server) GPU

Thread separator
 Component separator



Client-Server Stall of Sadness



Application Driver (Client) Driver (Server)

Thread separator
 Component separator



It's okay



Q: What's better than mapping in an unsynchronized manner?
A: Keeping around a pointer to GPU-visible memory *forever*.
Introducing: ARB_buffer_storage

ARB_buffer_storage



- Conceptually similar to ARB_texture_storage (but for buffers)
- Creates an immutable pointer to storage for a buffer
 - The pointer is immutable, the contents are not.
 - So BufferData cannot be called—BufferSubData is still okay.
- Allows for extra information at create time.
- For our usage, we care about the PERSISTENT and COHERENT bits.
 - **PERSISTENT:** Allow this buffer to be mapped while the GPU is using it.
 - COHERENT: Client writes to this buffer should be immediately visible to the GPU.
- http://www.opengl.org/registry/specs/ARB/buffer_storage.txt

ARB_buffer_storage cont'd



Also affects the mapping behavior (pass persistent and coherent bits to MapBufferRange)

- Persistently mapped buffers are good for:
 - Dynamic VB / IB data
 - Highly dynamic (~per draw call) uniform data
 - Multi_draw_indirect command buffers (more on this later)

Not a good fit for:

- Static geometry buffers
- Long lived uniform data (still should use BufferData or BufferSubData for this)

Armed with persistently mapped buffers



mOffset = 0;

// allParticleSize should be ~3x one frame's worth of particles
// to avoid stalling.

Update Loop (old and busted)



```
void UpdateParticleData(uint dstBuf) {
  BindBuffer(ARRAY BUFFER, dstBuf);
  access = MAP UNSYNCHRONIZED | MAP WRITE BIT;
  for particle in allParticles {
    dataSize = GetParticleSize(particle);
    void* dst = MapBuffer(ARRAY BUFFER, offset, dataSize, access);
    (*(Particle*)dst) = *particle;
    offset += dataSize;
    UnmapBuffer(ARRAY BUFFER);
  }
```

// Now render with everything.

};

Update Loop (new hotness)



void UpdateParticleData() {

```
for particle in allParticles {
   dataSize = GetParticleSize(particle);
```

mParticleDst[mOffset] = *particle; mOffset += dataSize; // Wrapping not shown

/ Now render with everything.

};

Test App



🖭 Test Window



Performance results



- 160,000 point sprites
- Specified in groups of 6 vertices (one particle at a time)
 - Synthetic (naturally)

Method	FPS	Particles / S
Map(UNSYNCHRONIZED)		219,040
BufferSubData		2,824,000
D3D11 Map(NO_OVERWRITE)		

Performance results



- 160,000 point sprites
- Specified in groups of 6 vertices (one particle at a time)
- Synthetic (naturally)

Method	FPS	Particles / S
Map(UNSYNCHRONIZED)		
BufferSubData		
D3D11 Map(NO_OVERWRITE)		
Map(COHERENT PERSISTENT)		

Room for improvement still, but much, much better.

The other shoe



- You are responsible for not stomping on data in flight.
- Why 3x?
 - 1x: What the GPU is using right now.
 - 2x: What the driver is holding, getting ready for the GPU to use.
 - 3x: What you are writing to.
- 3x should ~ guarantee enough buffer room*...
- Use fences to ensure that rendering is complete before you begin to write new data.

Fencing



- Use FenceSync to place a new fence.
- When ready to scribble over that memory again, use ClientWaitSync to ensure that memory is done.
 - ClientWaitSync will block the client thread until it is ready
 - So you should wrap this function with a performance counter
 - And complain to your log file (or resize the underlying buffer) if you frequently see stalls here
- For complete details on correct management of buffers with fencing, see Efficient Buffer Management [McDonald 2012]

Efficient Texture Management



Or "how to manage all texture memory myself"



Problem



Changing textures breaks batches.
Not all texture data is needed all the time

Texture data is large (typically the largest memory bucket for games)

Bindless solves this, but can hurt GPU performance

Too many different textures can fall out of TexHdr\$
Not a bindless problem per se

Terminology



- Reserve The act of allocating virtual memory
- Commit Tying a virtual memory allocation to a physical backing store (Physical memory)
- Texture Shape The characteristics of a texture that affect its memory consumption
 - Specifically: Height, Width, Depth, Surface Format, Mipmap Level Count

Texture Atlases

Old Solution

Problems

- Can impact art pipeline
- Texture wrap, border filtering
- Color bleeding in mip maps





Texture Arrays



- Introduced in GL 3.0, and D3D 10.
- Arrays of textures that are the same shape and format
- Typically can contain many "layers" (2048+)
- Filtering works as expected
- As does mipmapping!







Sparse Bindless Texture Arrays



Organize loose textures into Texture Arrays.

- Sparsely allocate Texture Arrays
 - Introducing ARB_sparse_texture
 - Consume virtual memory, but not physical memory
- Use Bindless handles to deal with as many arrays as needed! Introducing ARB_bindless_texture



ARB_sparse_texture

Applications get fine-grained control of physical memory for textures with large virtual allocations Inspired by Mega Texture Primary expected use cases: Sparse texture data
Texture paging

Delayed-loading assets

http://www.opengl.org/registry/specs/ARB/sparse_texture.txt



ARB_bindless_texture



Textures specified by GPU-visible "handle" (really an address)

Rather than by name and binding point

Can come from ~anywhere

- Uniforms
- Varying
- SSBO
- Other textures

Texture residency also application-controlled

- Residency is "does this live on the GPU or in sysmem?"
- https://www.opengl.org/registry/specs/ARB/bindless_texture.txt

Advantages



Artists work naturally

- No preprocessing required (no bake-step required)
 - Although preprocessing is helpful if ARB_sparse_texture is unavailable
- Reduce or eliminate TexHdr\$ thrashing
 - Even as compared to traditional texturing
- Programmers manage texture residency
- Works well with arbitrary streaming
- Faster on the CPU
- Faster on the GPU

Disadvantages



Texture addresses are now structs (96 bits).

- 64 bits for bindless handle
- 32 bits for slice index (could reduce this to 10 bits at a perf cost)
- ARB_sparse_texture implementations are a bit immature
 - Early adopters: please *bring us your bugs*.

ARB_sparse_texture requires base level be a multiple of tile size

- (Smaller is okay)
- Tile size is queried at runtime
- Textures that are power-of-2 should almost always be safe.

Implementation Overview



When creating a new texture...

Check to see if any suitable texture array exists

Texture arrays can contain a large number of textures of the same shape

Ex. Many TEXTURE 2Ds grouped into a single TEXTURE 2D ARRAY

If no suitable texture, create a new one.

Texture Container Creation (example)



- GetIntegerv(MAX_SPARSE_ARRAY_TEXTURE_LAYERS, maxLayers);
 - Choose a reasonable size (e.g. array size ~100MB virtual)
- If new internalFormat, choose page size
 - GetInternalformativ(..., internalformat, NUM_VIRTUAL_PAGE_SIZES, 1, &numIndexes);
 - Note: numIndexes can be 0, so have a plan
 - Iterate, select suitable pageSizeIndex
- BindTexture(TEXTURE_2D_ARRAY, newTexArray);
- TexParameteri(TEXTURE_SPARSE, TRUE);
- TexParameteri(VIRTUAL_PAGE_SIZE_INDEX, pageSizeIndex);
- Allocate the texture's virtual memory using TexStorage3D

Specifying Texture Data



- Using the located/created texture array from the previous step
- Allocate a layer as the location of our data
- For each mipmap level of the allocated layer:
 - Commit the entire mipmap level (using TexPageCommitment)
 - Specify actual texel data as usual for arrays
 - gl(Compressed|Copy|)TexSubImage3D
 - PBO updates are fine too



Freeing Textures



To free the texture, reverse the process:

- Use TexPageCommitment to mark the entire layer (slice) as free.
 - Do once for each mipmap level
 - Add the layer to the free list for future allocation


Combining with Bindless to eliminate binds



At container create time:

- Specify sampling parameters via SamplerParameter calls first
- Call GetTextureSamplerHandleARB to return a GPU-visible pointer to the texture+sampler container
- Call MakeTextureHandleResident to ensure the resource lives on the GPU
- At delete time, call MakeTextureHandleNonResident
- With bindless, you explicitly manage the GPU's working set

Using texture data in shaders



When a texture is needed with the default sampling parameters

Create a GLSL-visible TextureRef object:

struct TextureRef {
 sampler2DArray container;
 float slice;

};

When a texture is needed with custom sampling parameters
 Create a separate sampler object for the shader with the parameters
 Create a bindless handle to the pair using GetTextureSamplerHandle, then call MakeTextureHandleResident with the new value
 And fill out a TextureRef as above for usage by GLSL

C++ Code



Basic implementation (some details missing)

BSD licensed (use as you will)

https://github.com/nvMcJohn/apitest/blob/pdoane_newtests/sparse_bindless_texarray.h https://github.com/nvMcJohn/apitest/blob/pdoane_newtests/sparse_bindless_texarray.cpp

Increasing Draw Call Count



Let's draw all the calls!

All the Draw Calls!



Problem

- You want more draw calls of smaller objects.
- D3D is slow at this.
- Naïve GL is faster than D3D, but not fast enough.

XY Problem



- Y: How can I have more draw calls?
- X: You don't really care if it's more draw calls, right?
 - Really what you want is to be able to draw more small geometry groupings. More objects.

Well why didn't you just say so??



First, some background.

- What makes draw calls slow?
- Real world API usage
- Draw Call Cost Visualization

Some background



What causes slow draw calls?

- Validation is the biggest bucket (by far).
- Pre-validation is "difficult"
- "Every application does the same things."
 - Not really. Most applications are in completely disjoint states
 - Try this experiment: What is important to you?
 - Now ask your neighbor what's important to him.

Why is prevalidation difficult?



The GPU is an exceedingly complex state machine.
(Honestly, it's probably the most complex state machine in all of CS)
Any one of those states may have a problem that requires WAR
Usually the only problem is overall performance
But sometimes not. ^(B)
There are millions of tests covering NVIDIA GPU functionality.





How can app devs mitigate these costs?

- Minimize state changes.
 - All state changes are not created equal!
 - Cost of a draw call:

Small fixed cost + Cost of validation of changed state

Feels limiting...



Artists want lots of materials, and small amounts of geometry
 Even better: What if artists just didn't have to care about this?
 Ideal Programmer->Artist Interaction

"You make pretty art. I'll make it fit."

Relative costs of State Changes



- In decreasing cost...
- Render Target
- Program
- ROP
- Texture Bindings
- Vertex Format
- **UBO Bindings**
- Vertex Bindings
- Uniform Updates



Note: Not to scale

Real World API frequency



API usage looks roughly like this...

- Increasing Frequency of Change
 - Render Target (scene)
 - Per Scene Uniform Buffer + Textures
 - IB / VB and Input Layout
 - Shader (Material)
 - Per-material Uniform Buffer + Textures
 - Per-object Uniform Buffer + Textures
 - Per-piece Uniform Buffer + Textures
 - Draw

Draw Calls visualized







Draw Calls visualized (cont'd)





Read down, then right Black—no change



Goals



- Let's minimize validation costs without affecting artists
- Things we need to be fast (per app call frequency):
 - Uniform Updates and binding
 - Texture Updates and binding
- These happen most often in app, ergo driving them to ~0 should be a win.

Textures



Using Sparse Bindless Texture Arrays (as previously described) solves this.

- All textures are set before any drawing begins
- (No need to change textures between draw calls)
- Note that from the CPU's perspective, *just* using bindless is sufficient.

Eliminating Texture Binds -- visualized

Increasing Frequency of Change

- Render Target (scene)
- Per Scene Uniform Buffer + Textures
- IB / VB and Input Layout
- Shader (Material)
- Per-material Uniform Buffer + Textures
- Per-object Uniform Buffer + Textures
- Per-piece Uniform Buffer + Textures
- Draw









Boom!

Increasing Frequency of Change

- Render Target (scene)
- Per Scene Uniform Buffer
- IB / VB and Input Layout
- Shader (Material)
- Per-material Uniform Buffer
- Per-object Uniform Buffer
- Per-piece Uniform Buffer
- Draw













Typical Scene Graph Traversal

for obj in visibleObjectSet {
 update(buffer, obj);
 draw(obj);
}

Buffer updates (new hotness)



Typical Scene Graph Traversal

for obj in visibleObjectSet {
 update(bufferFragment, obj);
}

for obj in visibleObjectSet {
 draw(obj);

bufferFragma-wha?



Rather than one buffer per object, we share UBOs for many objects.

ie, given struct ObjectUniforms { /* ... */ };
 // Old (probably not explicitly instantiated,
 // just scattered in GLSL)
 ObjectUniforms uniformData;

// New

ObjectUniforms uniformData[ObjectsPerKickoff]; Use persistent mapping for even more win here! For large amounts of data (bones) consider SSBO. Introducing ARB_shader_storage_buffer_object

SSBO?



- Like "large" uniform buffer objects.
 - Minimum required size to claim support is 16M.
 - Accessed like uniforms in shader
- Support for better packing (std430)
 - Caveat: They are typically implemented in hardware as textures (and can introduce dependent texture reads)

Just one of a laundry list of things to consider, not to discourage use. http://www.opengl.org/registry/specs/ARB/shader_storage_buffer_object.txt

Eliminating Buffer Update Overhead



Increasing Frequency of Change Render Target (scene) Per Scene Uniform Buffer **IB / VB and Input Layout** Shader (Material) Per-material Uniform Buffer Per-object Uniform Buffer **Per-piece Uniform Buffer** Draw









Sweet!

Increasing Frequency of Change

- Render Target (scene)
- IB / VB and Input Layout
- Shader (Material)
- Draw (* each object)

Hrrrrmmmmm....





Vertex Format







- It'd be awesome if we could do all of those kickoffs at once.
- Validation is already only paid once
 - But we could just pay the constant startup cost once.
 - If only.....





- It'd be awesome if we could do all of those kickoffs at once.
- Validation is already only paid once
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- If only.....

Introducing ARB_multi_draw_indirect

ARB_multi_draw_indirect



Allows you to specify parameters to draw commands from a buffer.

- This means you can generate those parameters wide (on the CPU)
- Or even on the GPU, via compute program.
- http://www.opengl.org/registry/specs/ARB/multi_draw_indirect.txt

ARB_multi_draw_indirect cont'd



void MultiDrawElementsIndirect(enum mode,

enum type
const void* indirect,
sizei primcount,
sizei stride);

ARB_multi_draw_indirect cont'd



```
const ubyte * ptr = (const ubyte *)indirect;
```

```
for (i = 0; i < primcount; i++) {
```

```
DrawArraysIndirect(mode,
```

```
(DrawArraysIndirectCommand*)ptr);
```

```
if (stride == 0)
```

{



typedef struct {

- uint count;
- uint primCount;
- uint first;
- uint baseInstance;
- } DrawArraysIndirectCommand;

Knowing which shader data is mine



Use ARB_shader_draw_parameters, a necessary companion to ARB_multi_draw_indirect

Adds a builtin to the VS: DrawID (InstanceID already available)

- This tells you which command of a MultiDraw command is being executed.
- When not using MultiDraw, the builtin is specified to be 0.

Caveat: Right now, you have to pass this down to other shader stages as an interpolant.

Hoping to have that rectified via ARB or EXT extension "real soon now." http://www.opengl.org/registry/specs/ARB/shader_draw_parameters.txt

Applying everything



CPU Perf is massively better

- **5-30x increase in number of distinct objects / s**
- Interaction with driver is decreased ~75%

Note: GPU perf can be affected negatively (although not too badly)

As always: Profile, profile, profile.

Previous Results











Visualized Results







Where we came from











Conclusion



Go forth and work magnify.

Questions?



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